# THE ADVECTIVE-ACOUSTIC INSTABILITY IN TYPE II SUPERNOVAE

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**Abstract.** The puzzle of birth velocities of pulsars (pulsar kicks) could be solved by an asymmetric explosion of type II Supernovae. We propose a simple hydrodynamical mechanism in order to explain this asymmetry, through the advective-acoustic cycle (Foglizzo 2002): during the phase of stalled shock, an instability based on the cycle between advected perturbations (entropy / vorticity) and acoustic perturbations can develop between the shock and the surface of the nascent neutron star. Eigenfrequencies are computed numerically, improving the calculation of Houck & Chevalier (1992). The linear instability is dominated by a mode l=1, as observed in the numerical simulations of Blondin et al. (2003) and Scheck et al. (2004). The frequency dependence of the growth rate reveals the presence of the advective-acoustic cycle.

#### 1 Stationary accretion above a solid surface

We consider a shocked accretion flow onto a solid surface (where the velocity of the flow is null) at a constant accretion rate. A cooling region is located above the surface and described by the generic function  $\mathcal{L} \propto \rho^{\beta-\alpha}P^{\alpha}$  as in Houck & Chevalier (1992), hereafter HC92. The basic equations of the flow are the continuity equation, the Euler equation and the entropy equation. This latter is :  $\frac{\partial S}{\partial t} + (\vec{v}.\vec{\nabla})S + \frac{\mathcal{L}}{P} = 0$ , where a measure of the entropy is defined by  $S \equiv 1/(\gamma-1)\log(P/\rho^{\gamma})$ . These equations are perturbed and projected onto spherical harmonics  $Y_m^l$ .

The jump conditions at the shock  $r_{\rm sh}$  are given by the Rankine-Hugoniot relations for the stationary quantities. The perturbations at the shock are evaluated taking into account the displacement  $\Delta \xi$  of the shock position and its velocity  $\Delta v = -i\omega \Delta \xi$ . In particular, the perturbations of the transverse velocity are as

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follows (Landau & Lifchitz 1987):

$$\delta v_{\theta} = \frac{v_1 - v_2}{r_{\rm sh}} \frac{\partial \Delta \xi}{\partial \theta} \tag{1.1}$$

$$\delta v_{\phi} = \frac{v_1 - v_2}{r_{\rm sh} \sin \theta} \frac{\partial \Delta \xi}{\partial \phi} \tag{1.2}$$

where  $v_1$  and  $v_2$  are the pre-shock and post-shock velocities of the flow. These transverse velocity perturbations at the shock are not null for non-radial perturbations. This contrasts with Eq. (51) of HC92, who did not allow for transverse velocity perturbations at the shock.

The eigenfrequency  $\omega$  is a complex number  $(\omega_r, \omega_i)$  such that the velocity perturbation satisfies a wall type condition  $(\delta v/v = 0)$  at the surface of the accretor. The imaginary part  $\omega_i$  of the eigenfrequency is the growth rate of the perturbations.

## 2 Calculations of the eigenmodes

We performed several calculations of the fundamental modes (an example with  $\gamma = 5/3$ ,  $\alpha = 1/2$  and  $\beta = 2$  is shown in Fig. 1). The mode l = 1 is always the most unstable. This result differs from the analysis made by HC92 because of the error in their boundary conditions at the shock.

The advective-acoustic instability is based on the cycle between advected perturbations (entropy / vorticity) and acoustic perturbations between the shock and the surface. A reference timescale  $\tau$  for this mechanism is equal to the accretion time from the shock to the coupling region near the surface plus the time for an acoustic wave to reach the shock :

$$\tau \equiv \int_{r_*}^{r_{\rm sh}} \frac{1}{1 - \mathcal{M}} \frac{dr}{|v|} \tag{2.1}$$

The acoustic time  $t_{\rm ac}$  is defined by the time needed for an acoustic wave to propagate from the shock to the accretor and then back up to the shock,  $\omega_{\rm ac} \equiv 2\pi/t_{\rm ac}$  being the pulsation associated to this acoustic time:

$$t_{\rm ac} \equiv \int_{r}^{r_{\rm sh}} \frac{2}{1 - \mathcal{M}^2} \frac{dr}{c} \tag{2.2}$$

On Figs. 1, 2, the growth rate  $\omega_i$  is at best comparable to  $\omega_{\rm sh} \sim 1/\tau$  and the pulsation  $\omega_r$  of the fundamental unstable modes is close to  $2\pi/\tau$ , as expected in the advective-acoustic mechanism. The frequency dependence of the growth rate of the eigenmodes shows an oscillatory behaviour with a period comparable to  $\omega_{\rm ac}$  (Fig. 2). Such oscillations are expected in the advective-acoustic instability, as a consequence of the modulation of the advective-acoustic cycle by the purely acoustic cycle (Foglizzo 2002). This interpretation is confirmed by measuring the

ratio  $\tau/t_{\rm ac} \sim 4.5-6.5$  which is comparable to the number of modes found per oscillations (Foglizzo 2002).

We note that for big cavities, the most unstable eigenmodes correspond to low frequencies, in the "pseudo-sound" regime ( $\omega_r < \omega_{\rm ac}$ ). Unstable eigenmodes are also found in the acoustic regime ( $\omega_r > \omega_{\rm ac}$ ), with a smaller growth rate however (Fig. 2).

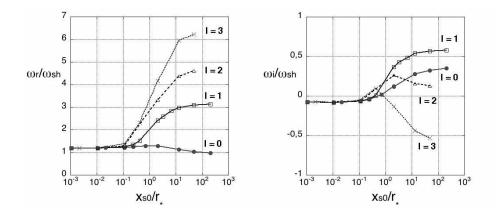
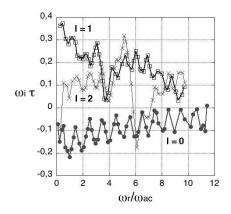


Fig. 1. For  $\gamma = 5/3$ ,  $\alpha = 1/2$  and  $\beta = 2$ , numerical calculations of the frequency  $\omega_r$  and the growth rate  $\omega_i$  in units of  $\omega_{\rm sh} \equiv -v_{\rm sh}/(r_{\rm sh}-r_*)$  of the fundamental modes l=0,1,2,3 depending on the size of the cavity  $x_{s0}/r_* \equiv (r_{\rm sh}-r_*)/r_*$ , as in Houck & Chevalier (1992). The degree l of the modes is indicated on each curve.



**Fig. 2.** For  $\gamma = 4/3$ ,  $\beta = 2$ ,  $\alpha = 1/2$ , and a cavity  $r_{\rm sh}/r_* \sim 12$ , numerical calculations of the frequency  $\omega_r$  in units of  $\omega_{\rm ac}$  and the growth rate  $\omega_i$  in units of  $\omega_{\rm sh}$  of radial l = 0 and non-radial l = 1, 2 eigenmodes.

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On Fig. 3, for  $\gamma=4/3$  and a cooling function described by  $\alpha=6$ ,  $\beta=1$ , relevant to the phase of a stalled shock in type II Supernovae (Bethe & Wilson 1985), an unstable mode l=1 can also be found for big enough cavities  $(r_{\rm sh}/r_*\gtrsim 3.5)$ . A frequency dependence study, still in progress, shows unstable modes l=1 both in the "pseudo-sound" regime and in the acoustic regime. The radial modes (l=0) are always stable.

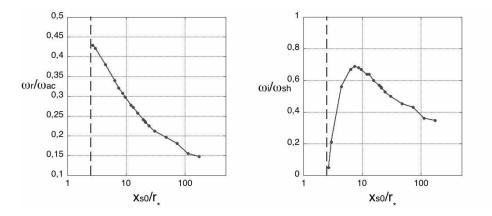


Fig. 3. For  $\gamma=4/3$ ,  $\alpha=6$  and  $\beta=1$ , numerical calculations of the frequency  $\omega_r$  in units of  $\omega_{\rm ac}$  and the growth rate  $\omega_i$  in units of  $\omega_{\rm sh}\equiv -v_{\rm sh}/(r_{\rm sh}-r_*)$ , of the first unstable mode l=1, depending on the size of the cavity  $x_{s0}/r_*=(r_{\rm sh}-r_*)/r_*$ . The vertical dashed line correspond to  $r_{\rm sh}/r_*=3.5$  ( $x_{s0}/r_*=2.5$ ).

### 3 Conclusion

The stalled accretion shock above a neutron star is unstable, with a domination of a mode l=1 if the shock radius is large enough. The instability is interpreted as an advective-acoustic cycle modulated by a purely acoustic cycle. The instability is also found when the cooling function mimics neutrino cooling in type II Supernovae. The advective-acoustic cycle is thus a good candidate to seed an asymmetric explosion which could lead to an important birth velocity of the neutron star.

#### References

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